

$$I_C = \frac{V_{CC} - V_{BE}}{R}$$

J.S.
02/07/11

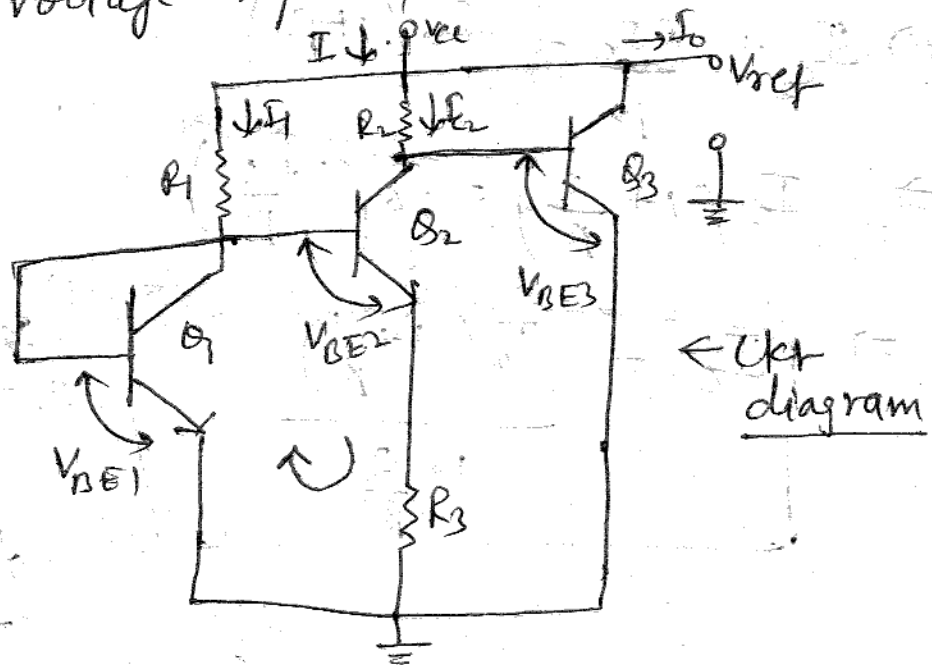
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BAND GAP VOLTAGE REFERENCE

→ It is used for circuit operating supply voltage below 5 volt or less.

Bandgap voltage $\left\{ \begin{array}{l} Ge \rightarrow 1.1 \text{ volt} \\ Si \rightarrow 0.78 \text{ volt} \end{array} \right.$

Since Zener diode and temperature compensated avalanche diode have breakdown voltage of 6 to 7V. So the supply voltage required will be low



Applying KVL through R_3 , considering ΔV_{BE}

$$V_{BE1} + V_{BE2}$$

$$V_{R3} - V_{BE1} + V_{BE2} = 0$$

$$\Rightarrow V_{R3} = V_{BE1} - V_{BE2}$$

$$V_{R3} = \Delta V_{BE}$$

Eber Moll's Equation :-

$$I_{C1} = I_S e^{V_{BE1}/V_T} \quad \text{--- (1)}$$

$$I_{C2} = I_S e^{V_{BE2}/V_T} \quad \text{--- (2)}$$

I_S = Collector Saturation Current.

$$V_T = kT$$

k = Boltzman Constant

$$\frac{I_{C1}}{I_{C2}} = e^{(V_{BE1} - V_{BE2})/V_T}$$

$$\Rightarrow \ln \frac{I_{C1}}{I_{C2}} = \frac{V_{BE1} - V_{BE2}}{V_T}$$

$$\Rightarrow V_{BE1} - V_{BE2} = V_T \ln \left(\frac{I_{C1}}{I_{C2}} \right)$$

$$\Rightarrow V_{R3} = V_T \ln \left(\frac{I_{C1}}{I_{C2}} \right) \quad \text{--- Eqn (1)'}$$

We know,

$$I_E = I_B + I_C \quad \text{for transistor } B_2$$

$$\text{also } I_{E2} = I_{C2} \quad (\text{neglecting base current})$$

$$I_{E2} = \text{Current through } R_3$$

$$I_{E2} = I_{R3}$$

$$\Rightarrow \boxed{I_{R3} = I_{C2}}$$

Apply KVL through R_2 ,

taking V_{BE3} & V_{ref}

$$-V_{BE3} - I_{C2} R_2 + V_{ref} = 0$$

$$\Rightarrow V_{ref} = V_{BE3} + (I_{C2}) R_2$$

$$V_{R3} = I_{R3} \cdot R_3$$

$$\Rightarrow \frac{V_{R3}}{R_3} = I_{R3}$$

$$\Rightarrow V_{ref} = V_{BE3} + \left(V_T \ln \frac{I_{C4}}{I_{C2}} \right) \frac{R_2}{R_3}$$

Differentiating above eqⁿ w.r.t T .

$$\frac{V_{ref}}{dT} = \frac{dV_{BE3}}{dT} + \frac{d}{dT} \left(kT \ln \frac{I_{e1}}{I_{e2}} \cdot \frac{R_2}{R_3} \right)$$

Diff of volt. w.r to Temp \rightarrow

$$\Rightarrow = \frac{dV_{BE3}}{dT} + \frac{R_2}{R_3} \cdot k \ln \frac{I_{e1}}{I_{e2}}$$

$$\Rightarrow \boxed{\frac{V_{ref}}{dT} = \frac{dV_{BE3}}{dT} + \frac{R_2}{R_3} \cdot k \ln \frac{I_{e1}}{I_{e2}}}$$

$$\Rightarrow \frac{dV_{ref}}{dT} = TC(V_{BE})$$

\uparrow
 Temp Coefficient of V_{BE}

According to PN junction Theory :-

$$TC(V_{BE}) = \frac{dV_{BE}}{dT}$$

$$\boxed{TC(V_{BE}) = \frac{V_{BE} - (V_{G0} + 3kT)}{T}}$$

V_{G0} = Bandgap voltage

$$TC(V_{BE}) = - \left[\frac{V_{G0} - V_{BE} + 3k}{T} \right] \text{--- (A)}$$

$$V_{ref} = V_{BE} + \frac{R_2}{R_3} \ln \left(\frac{I_{q1}}{I_{q2}} \right)$$

$$\frac{dV_{ref}}{dT} = \frac{dV_{BE}}{dT} + \frac{R_2}{R_3} k \ln \left(\frac{I_{q1}}{I_{q2}} \right)$$

$$= TC(V_{BE}) + \frac{R_2}{R_3} k \ln \left(\frac{I_{q1}}{I_{q2}} \right) \quad \text{--- (2)}$$

sub (A) in (3)

$$\frac{dV_{ref}}{dT} = - \left[\frac{V_{G10} - V_{BE} + 3kT}{T} \right] + \frac{R_2}{R_3} k \ln \left(\frac{I_{q1}}{I_{q2}} \right)$$

Always, $TC(V_{BE}) = 0 \Rightarrow \frac{dV_{ref}}{dT} = 0$

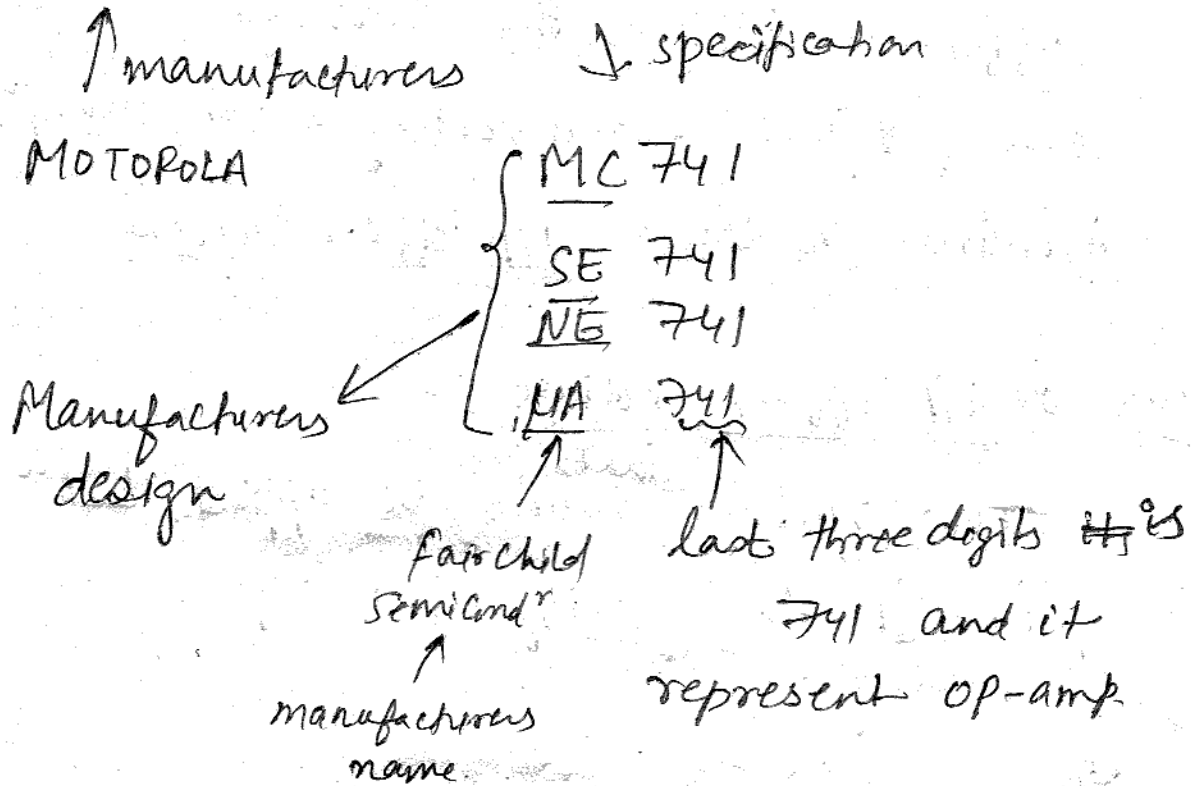
$$\Rightarrow \frac{dV_{ref}}{dT} = \frac{R_2}{R_3} k \ln \left(\frac{I_{q1}}{I_{q2}} \right)$$

$$- \left[\frac{V_{G10} - V_{BE} + 3kT}{T} \right] = - \frac{R_2}{R_3} k \ln \frac{I_{q1}}{I_{q2}}$$

$$\Rightarrow V_{G10} - V_{BE} + 3kT = \frac{R_2}{R_3} kT \ln \frac{I_{q1}}{I_{q2}}$$

$$\Rightarrow \boxed{V_{G10} - V_{BE} = \frac{R_2}{R_3} kT \ln \frac{I_{q1}}{I_{q2}} - 3kT}$$

Monolithic IC op-amp :-



Ideal Char of op-amp :-

$$A_{OL} = \infty$$

$$R_i = \text{i/p impedance}$$

$$R_i = \infty$$

$$R_o = 0$$

$$BW = \infty$$

Non Ideal Characteristics of op-amp

D.c Characteristic :-

(i) I/P biased Current :- The average of the current entering into +ve & -ve terminal, of an op-amp, is known as i/p biased current.

2) I/P offset Current :- The algebraic difference between the current entering & into the inverting & non-inverting terminal is called I/P offset Current

3) I/P offset voltage :-
The voltage ^{that} must be applied betⁿ the I/P to nullify the O/P

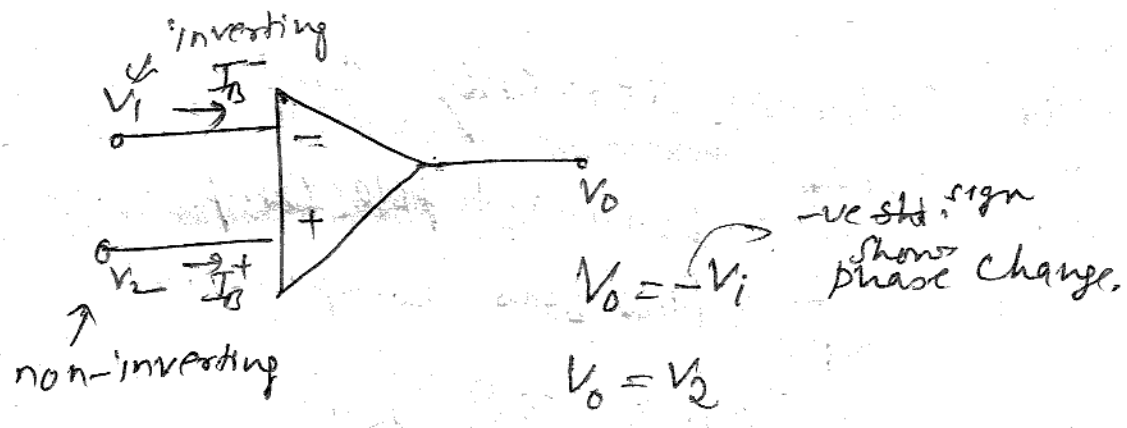
4) Total O/P offset voltage :- The O/P voltage produced at the O/P due to I/P biased current, or I/P offset voltage.

5) Thermal drift :- The average rate of change of I/P offset voltage per unit change in temperature.

~~6)~~

A-c Characteristics :-

- (i) Frequency Response
- (ii) Band width
- (iii) Slew Rate



for ideal,

$$V_1 = V_2 = 0,$$
$$V_o = 0.$$

FREQUENCY COMPENSATION

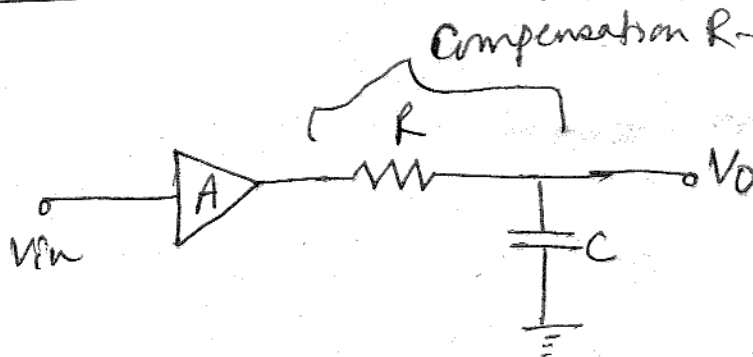
↑ BW

↓ open loop gain

(i) External frequency comp.

- Dominant Pole Comp.
- Pole zero Compensation
- Miller effect "

Dominant Pole Compensation :-



$$A = \frac{A_{OL}}{(1 + jf/f_1)(1 + jf/f_2)(1 + jf/f_3)}$$

Where

A = uncompensated gain

— Deg.

$$\frac{V_o}{V_{in}} = A \cdot \frac{z_c}{z_R + z_c}$$

$$z_c = \frac{1}{j\omega C}$$

$$z_R = R$$

$$\frac{V_o}{V_{in}} = A \cdot \frac{1/j\omega C}{R + 1/j\omega C}$$

$$= \frac{A}{1 + j\omega RC}$$

$$= \frac{A}{1 + j f / f_d}$$

$$f_d = \frac{1}{2\pi RC}$$

dominant frequency

② eq.

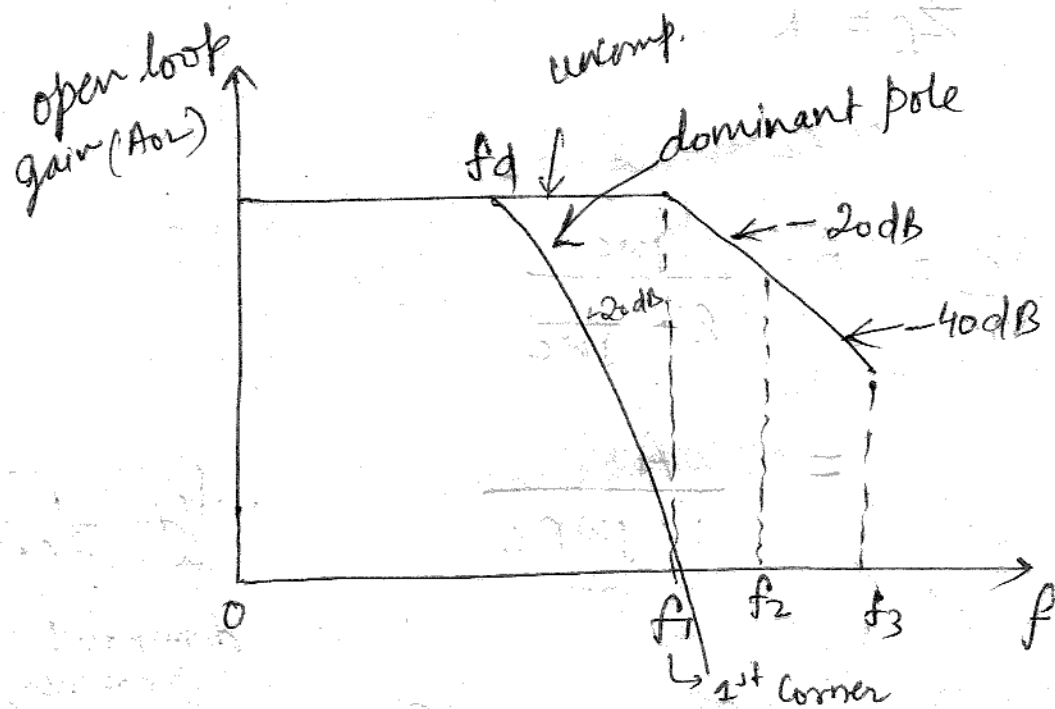
Sub ① in ②

$$\frac{V_o}{V_{in}} \Rightarrow \frac{A}{1 + j f / f_d} = \frac{A_{OL}}{(1 + j f / f_{p1})(1 + j f / f_{p2})(1 + j f / f_{p3})}$$

$$\Rightarrow \frac{V_o}{V_{in}} = \frac{A_{OL}}{(1 + j f / f_{p1})(1 + j f / f_{p2})(1 + j f / f_{p3})}$$

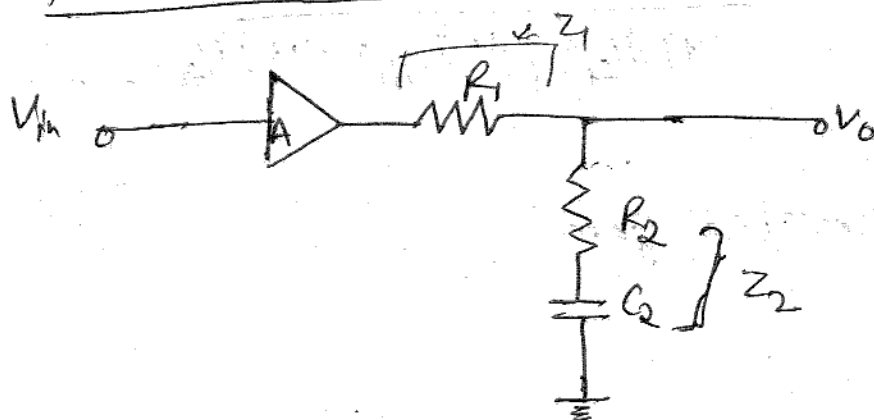
Compensated gain

The capacitance 'C' is chosen so that ~~not~~ modify loop gain drops to 0dB with a slope of -2dB.



The dominant pole is selected so that the compensated transfer function goes to 0dB and at 1st corner frequency with a slope of -2dB.

Pole Zero Compensation :-



$$\frac{V_o}{V_{in}} = A \frac{z_2}{z_1 + z_2}$$

$$A = \frac{A_{OL}}{(1+jf/f_0)(1+jf/f_1)(1+jf/f_2)(1+jf/f_3)}$$

$$\frac{V_o}{V_{in}} = A \frac{R_2 + \frac{1}{j\omega C_2}}{R_1 + R_2 + \frac{1}{j\omega C_2}}$$

$$= A \frac{1 + j\omega R_2 C_2}{1 + j\omega C_2 (R_1 + R_2)}$$

$$= A \frac{1 + j(f/f_2)}{1 + j(f/f_0)}$$

$$= \frac{A_{OL} (1 + jf/f_2)}{(1 + jf/f_0)(1 + jf/f_1)(1 + jf/f_2)(1 + jf/f_3)}$$

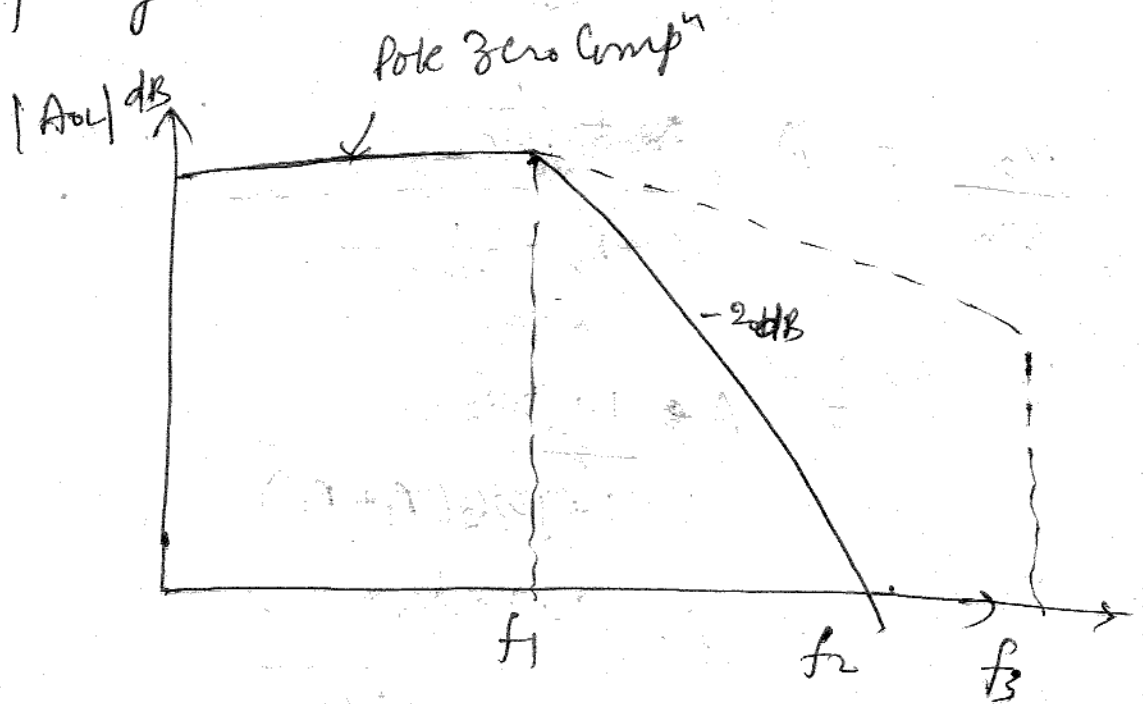
$$f_2 = \frac{1}{2\pi R_2 C_2}$$

$$f_0 = \frac{1}{2\pi C_2 (R_1 + R_2)}$$

$$\frac{V_o}{V_{in}} = \frac{A_{OL}}{(1 + jf/f_0)(1 + jf/f_1)(1 + jf/f_3)}$$

$$0 < f_0 < f_1 < f_2 < f_3$$

The Compensating n/w^c is designed to produce a zero at 1st corner frequency and a pole at 2nd corner frequency



Pole at f_2

Zero at f_1

↳ Internal Compensation

To ↑ Bandwidth, Compensation techniques are used in such cases internally

Compensated op-amp called

Compensated op-amp can be employed.

741

↳ Internally Compensated op-amp

Op-amp 741 internally contain capacitors of 30 pf. This internally compensating capacitor has open loop gain at -20dB that gives the stable characteristics of op-amp

SLEW RATE :- It is the rate of change of o/p voltage with respect to time

$$S = \frac{\Delta V_o}{\Delta t}$$

unit \rightarrow volt/ μ sec

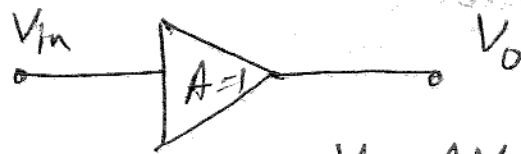
The Slew rate is caused due to limiting charging rate of compensating capacitor.

$$C = \frac{I}{V}$$

The Slew rate is maximum internal capacitor charging current is known more

then, $\frac{dV_c}{dt} = \frac{I}{C}$

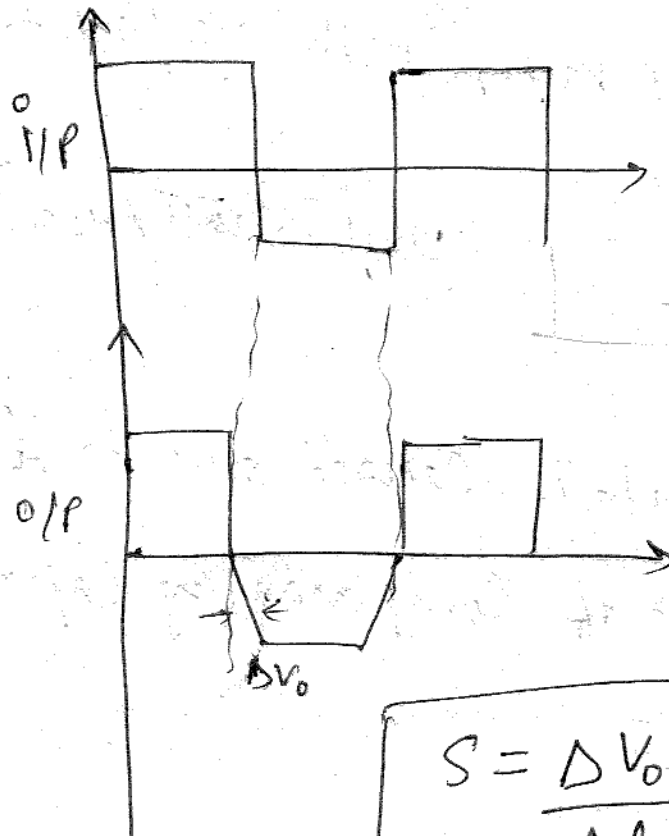
$$\frac{dV_c}{dt} = \frac{I_{max}}{C}$$



$$V_o = AV_{in}$$

$$V_o = V_{in}$$

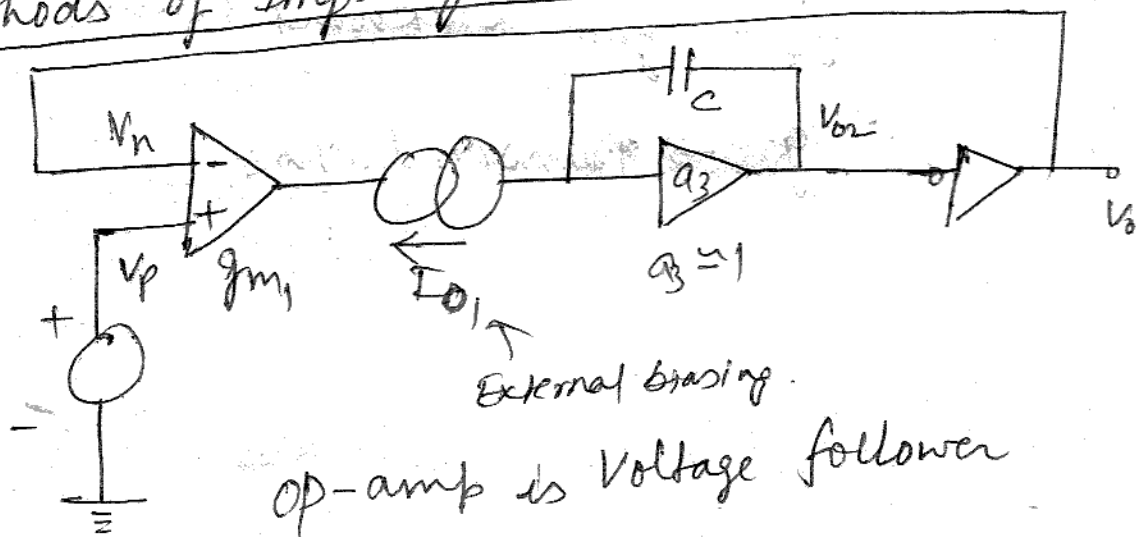
$$A=1$$



$$S = \frac{\Delta V_o}{\Delta t}$$

Ideally skew rate should be ~~∞~~ infinite for better performance of op-amp

Methods of Improving skew rate :- ^{Baseshi}



When ~~the~~ i/p over drives, the i/p stage,

$$I_{max} = I_{01} (sat)$$

The saturation of i/p stage remains ^{Slew} ~~slow~~ rate bcoz under saturatⁿ condⁿ the rate at which capacitor charges & discharges is max^m.

$$\frac{I_{01} (sat)}{C} = \frac{dV_{02}}{dt}$$

$$S = \frac{I_{01} (sat)}{g_m} f_t$$

$I_{o1}(\text{sat}) \uparrow$ or $g_m \downarrow$

~~f_t~~ $f_t \uparrow$

~~f_t~~ represents

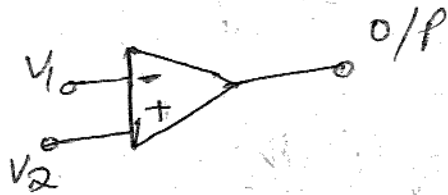
$f_t \rightarrow$ gain backward product

$g_m \rightarrow$ Transconductance

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UNIT 2

APPLICATIONS OF OP-AMP



$V_1 \rightarrow$ Inverting

$V_2 \rightarrow$ non-inverting

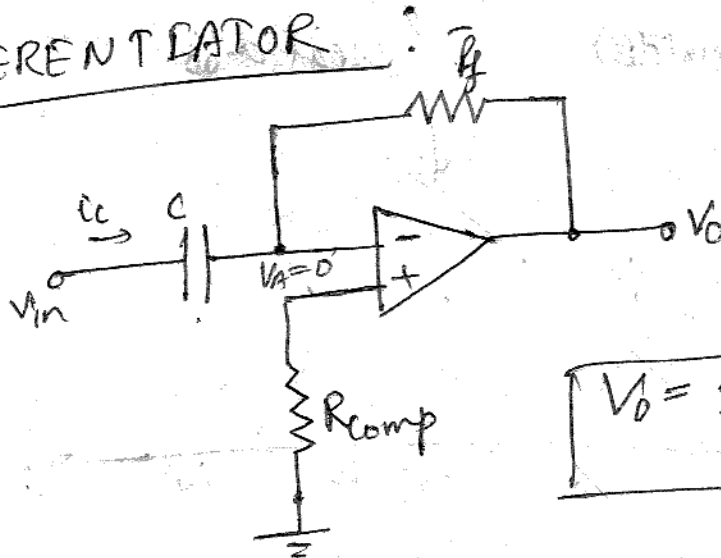
(i) Differentiator

(ii) Integrator

$V_0 = -V_1$

$V_2 = V_1$

DIFFERENTIATOR



$V_0 = \frac{dV_i}{dt}$

Analysis :-

$I_B = 0$

$V_A = 0$

$I_B =$ Biased Current

At node A, $V_A = 0$

KCL at node A



$C \frac{d(V_i - V_A)}{dt} + R_f V_0 = 0$

$$C \frac{dv_i}{dt} + R_f \frac{v_o}{R_f} = 0$$

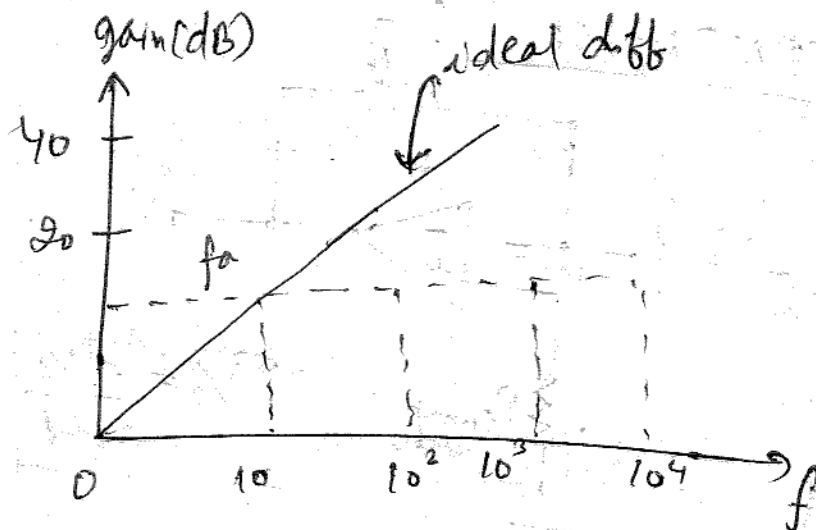
$$R_f \frac{v_o}{R_o} = -C \frac{dv_i}{dt}$$

$$v_o = \frac{-C R_f}{R_o} \frac{dv_i}{dt}$$

$$v_o = -R_f C \frac{dv_o}{dt}$$

$$v_o = (-R_f C) \frac{dv_i}{dt}$$

Frequency Response :-



$$v_o(t) =$$

$$v_o(t) = -R_f C \left(\frac{dv_i}{dt} \right)$$

Apply Laplace transform,

$$v_o(s) = -R_f C s v_i(s)$$

$$v_o(j\omega) = -R_f C j\omega v_o(j\omega)$$

$$\frac{v_o(j\omega)}{v_i(j\omega)} = -R_f C j\omega$$

$$G = -jf/f_a$$

Substitute $f_a = \frac{1}{2\pi R_f C}$

$$\frac{V_o(j\omega)}{V_i(j\omega)} = -jf/f_a$$

$$|A| = |-jf/f_a|$$

$$|A| = \frac{f}{f_a}$$

$$f < f_a \Rightarrow \text{gain } (-dB)$$

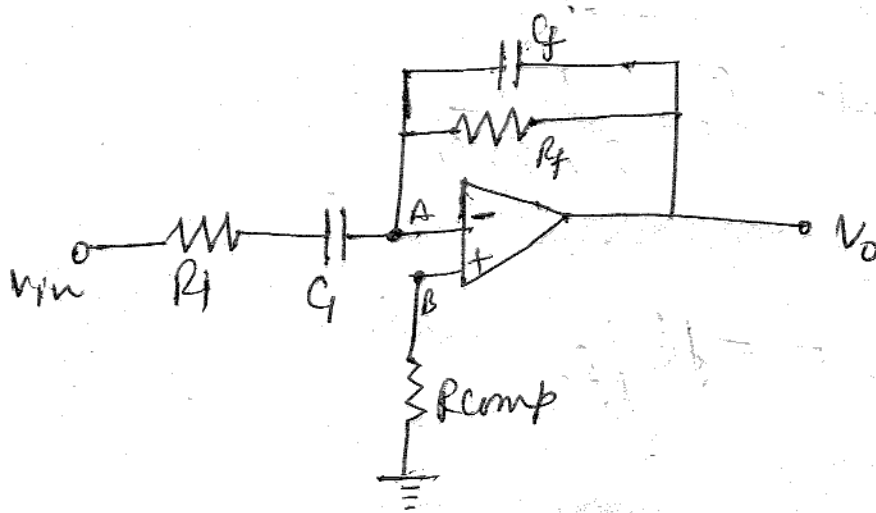
$$f > f_a \rightarrow \text{gain } (+dB)$$

$f_a =$ corner frequency.

Disadvantage of Ideal Differentiator

- (i) As ~~gain~~ ^{freq} \uparrow , gain \uparrow , for high frequency differentiator becomes unstable and goes into oscillation.
- (ii) $1/P$ impedance $X_c \downarrow$, as frequency \uparrow , this makes the circuit very sensitive to noise.

Practical Differentiator



$$V_A = V_B = 0$$

Apply KCL at node 'A'

$$\frac{V_{in}}{R_1} + C_1 \frac{dV_{in}}{dt} + (C_f \parallel R_f) V_o = 0$$

$$\Rightarrow \frac{V_o(s)}{V_i(s)} = \frac{s R_f C_1}{(1 + s R_f C_f)(1 + s R_1 C_1)}$$

Take $R_f C_f = R_1 C_1$

$$\frac{V_o(s)}{V_i(s)} = \frac{s R_f C_f}{(1 + s R_f C_f)^2}$$

$$\Rightarrow \frac{V_o(s)}{V_i(s)} = \frac{j\omega R_f C_f}{(1 + j\omega R_f C_f)^2}$$

$$= \frac{j 2\pi f R_f C_f}{(1 + j 2\pi f R_f C_f)^2}$$

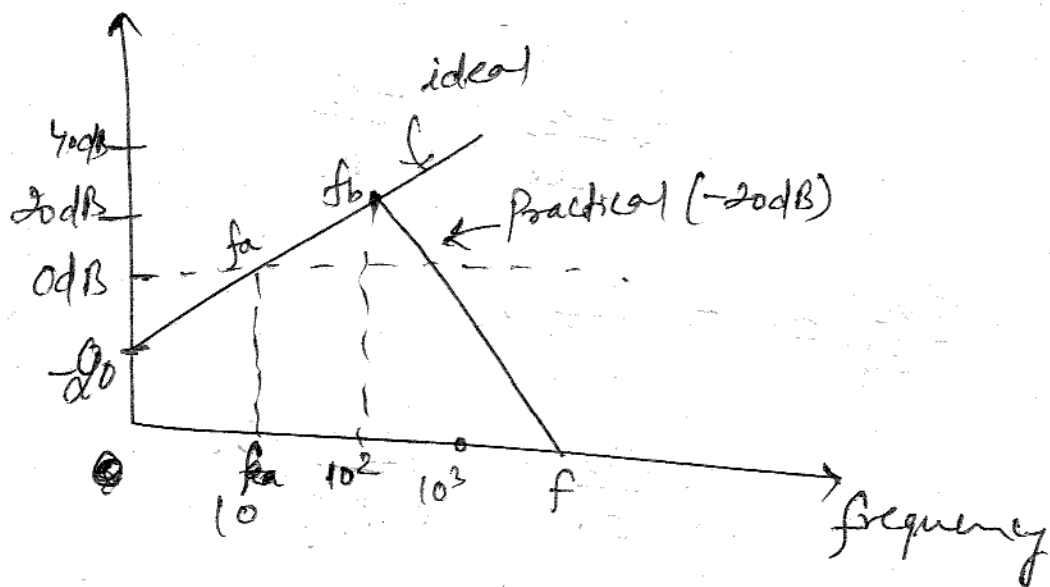
$$(1 + j 2\pi f R_f C_f)^2$$

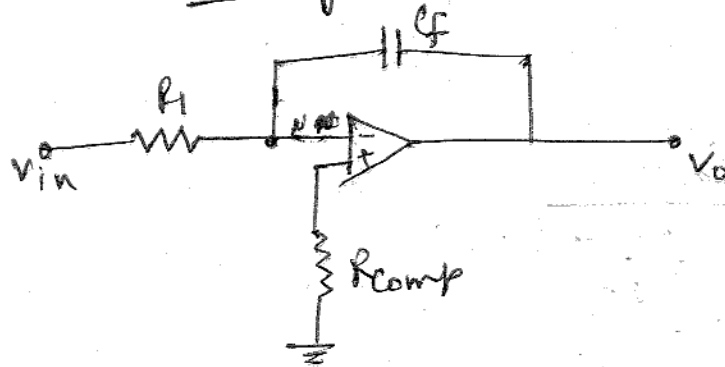
$$\frac{V_o(s)}{V_i(s)} = \frac{j f / f_a}{(1 + j f / f_b)^2}$$

$$|A| = \frac{f / f_a}{(1 + f / f_b)^2}$$

$$|A| = \frac{f / f_a}{1 + (f / f_b)^2}$$

Frequency Response



Integrator

Apply KCL at node 'A'

~~$$\frac{v_i - v_A}{R_1} + C_f \frac{dv_o}{dt} = 0$$~~

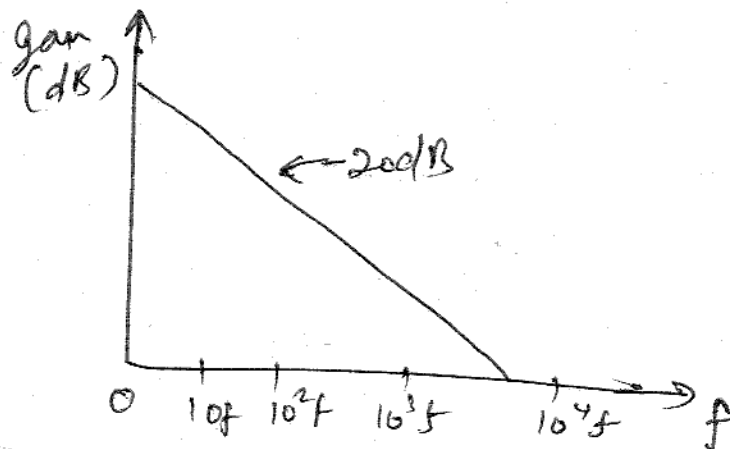
$$\frac{v_i}{R_1} + C_f \frac{dv_o}{dt} = 0$$

$$C_f \frac{dv_o}{dt} = -\frac{v_i}{R_1}$$

$$\frac{dv_o}{dt} = -\frac{1}{R_1 C_f} v_i$$

$$\int \frac{dv_o}{dt} = \int -\frac{1}{R_1 C_f} v_i$$

Freq. Response



i) As the gain of integrator is ∞ , with freq \uparrow ,
the integrator ckt will not have frequency
as differentiator

ii) At low frequency, gain becomes ∞ ,