

Fig 3.10.1: Polar plot of $G(j\omega) = 1/[j\omega(1+j\omega)^2]$ (using polar coordinates)

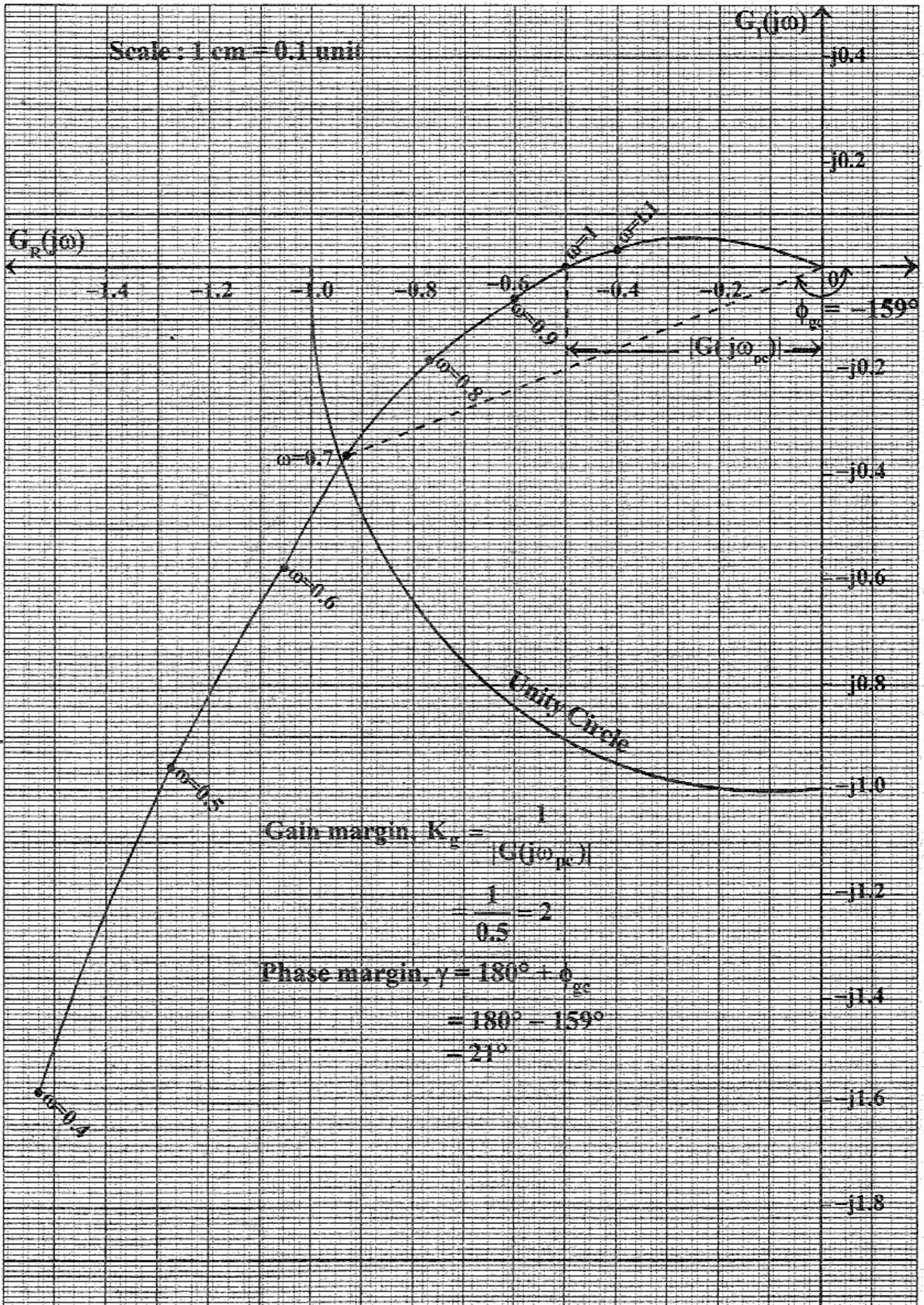


Fig 3.10.2: Polar plot of $G(j\omega) = 1/[j\omega(1+j\omega)^2]$ (using rectangular coordinates)

EXAMPLE 3.11

Consider a unity feedback system having an open loop transfer function $G(s) = \frac{K}{s(1+0.2s)(1+0.05s)}$.

Sketch the polar plot and determine the value of K so that (i) Gain margin is 18 db (ii) Phase margin is 60° .

SOLUTION

Given that, $G(s) = \frac{K}{s(1+0.2s)(1+0.05s)}$. The polar plot is sketched by taking $K = 1$.

$$\therefore \text{Put } K = 1 \text{ and } s = j\omega \text{ in } G(s). \therefore G(j\omega) = \frac{1}{j\omega(1+j0.2\omega)(1+j0.05\omega)}$$

The corner frequencies are $\omega_{c1} = 1/0.2 = 5 \text{ rad/sec}$ and $\omega_{c2} = 1/0.05 = 20 \text{ rad/sec}$. The magnitude and phase angle of $G(j\omega)$ are calculated for various frequencies and tabulated in table-1. Using polar to rectangular conversion the polar coordinates listed in table-1 are converted to rectangular coordinates and tabulated in table-2. The polar plot using polar coordinates is sketched on a polar graph sheet as shown in fig 3.11.1. Polar plot using rectangular coordinates is sketched on an ordinary graph sheet as shown in fig 3.11.2.

$$\begin{aligned} G(j\omega) &= \frac{1}{j\omega(1+j0.2\omega)(1+j0.05\omega)} \\ &= \frac{1}{\omega \angle 90^\circ \sqrt{1+(0.2\omega)^2} \angle \tan^{-1}0.2\omega \sqrt{1+(0.05\omega)^2} \angle \tan^{-1}0.05\omega} \\ &= \frac{1}{\omega \sqrt{1+(0.2\omega)^2} \sqrt{1+(0.05\omega)^2}} \angle (-90^\circ - \tan^{-1}0.2\omega - \tan^{-1}0.05\omega) \\ \therefore |G(j\omega)| &= \frac{1}{\omega \sqrt{1+(0.2\omega)^2} \sqrt{1+(0.05\omega)^2}} \quad \text{and} \quad \angle G(j\omega) = -90^\circ - \tan^{-1}0.2\omega - \tan^{-1}0.05\omega \end{aligned}$$

TABLE-1: Magnitude and Phase of $G(j\omega)$ at Various Frequencies

ω rad/sec	0.6	0.8	1	2	3	4
$ G(j\omega) $	1.65	1.23	1.0	0.5	0.3	0.2
$\angle G(j\omega)$ deg	-98	-101	-104	-117.5	-129.4	-140

ω rad/sec	5	6	7	9	10	11	14
$ G(j\omega) $	0.14	0.1	0.07	0.05	0.04	0.03	0.02
$\angle G(j\omega)$ deg	-149	-157	-164	-176	-180	-184	-195

TABLE-2: Real and Imaginary Parts of $G(j\omega)$ at Various Frequencies

ω rad/sec	0.6	0.8	1	2	3	4
$G_R(j\omega)$	-0.23	-0.23	-0.24	-0.23	-0.19	-0.15
$G_I(j\omega)$	-1.63	-1.21	-0.97	-0.44	-0.23	-0.13

ω rad/sec	5	6	7	9	10	11	14
$G_R(j\omega)$	-0.120	-0.092	-0.067	-0.050	-0.04	-0.030	-0.019
$G_I(j\omega)$	-0.072	-0.039	-0.019	-0.0034	0	0.002	0.005

In the polar plot shown in fig 3.11.1 and 3.11.2 there are two plots, marked as curve-I and curve-II. These two loci are sketched with different scales to clearly determine the gain margin and phase margin.

From the polar plot, with $K = 1$,

Gain margin, $K_g = 1/0.04 = 25$.

Gain margin in db = $20 \log 25 = 28$ db.

Phase margin, $\gamma = 76^\circ$.

Case (i)

With $K = 1$, let $G(j\omega)$ cut the -180° axis at point B and gain corresponding to that point be G_B . From the polar plot $G_B = 0.04$. The gain margin of 28 db with $K = 1$ has to be reduced to 18 db and so K has to be increased to a value greater than one.

Let G_A be the gain at -180° for a gain margin of 18 db.

$$\text{Now, } 20 \log \frac{1}{G_A} = 18 \quad \Rightarrow \quad \log \frac{1}{G_A} = \frac{18}{20} \quad \Rightarrow \quad \frac{1}{G_A} = 10^{18/20}$$

$$\therefore G_A = \frac{1}{10^{18/20}} = 0.125$$

$$\text{The value of } K \text{ is given by, } K = \frac{G_A}{G_B} = \frac{0.125}{0.04} = 3.125$$

Case (ii)

With $K = 1$, the phase margin is 76° . This has to be reduced to 60° . Hence gain has to be increased.

Let ϕ_{gc2} be the phase of $G(j\omega)$ for a phase margin of 60°

$$\therefore 60^\circ = 180^\circ + \phi_{gc2}$$

$$\phi_{gc2} = 60^\circ - 180^\circ = -120^\circ$$

In the polar plot the -120° line cut the locus of $G(j\omega)$ at point C and cut the unity circle at point D.

Let, G_C = Magnitude of $G(j\omega)$ at point C.

G_D = Magnitude of $G(j\omega)$ at point D.

From the polar plot, $G_C = 0.425$ and $G_D = 1$.

$$\text{Now, } K = \frac{G_D}{G_C} = \frac{1}{0.425} = 2.353$$

RESULT

- When $K = 1$, Gain margin, $K_g = 25$
Gain margin in db = 28db
- When $K = 1$, Phase margin, $\gamma = 76^\circ$
- For a gain margin of 18 db, $K = 3.125$
- For a phase margin of 60° , $K = 2.353$

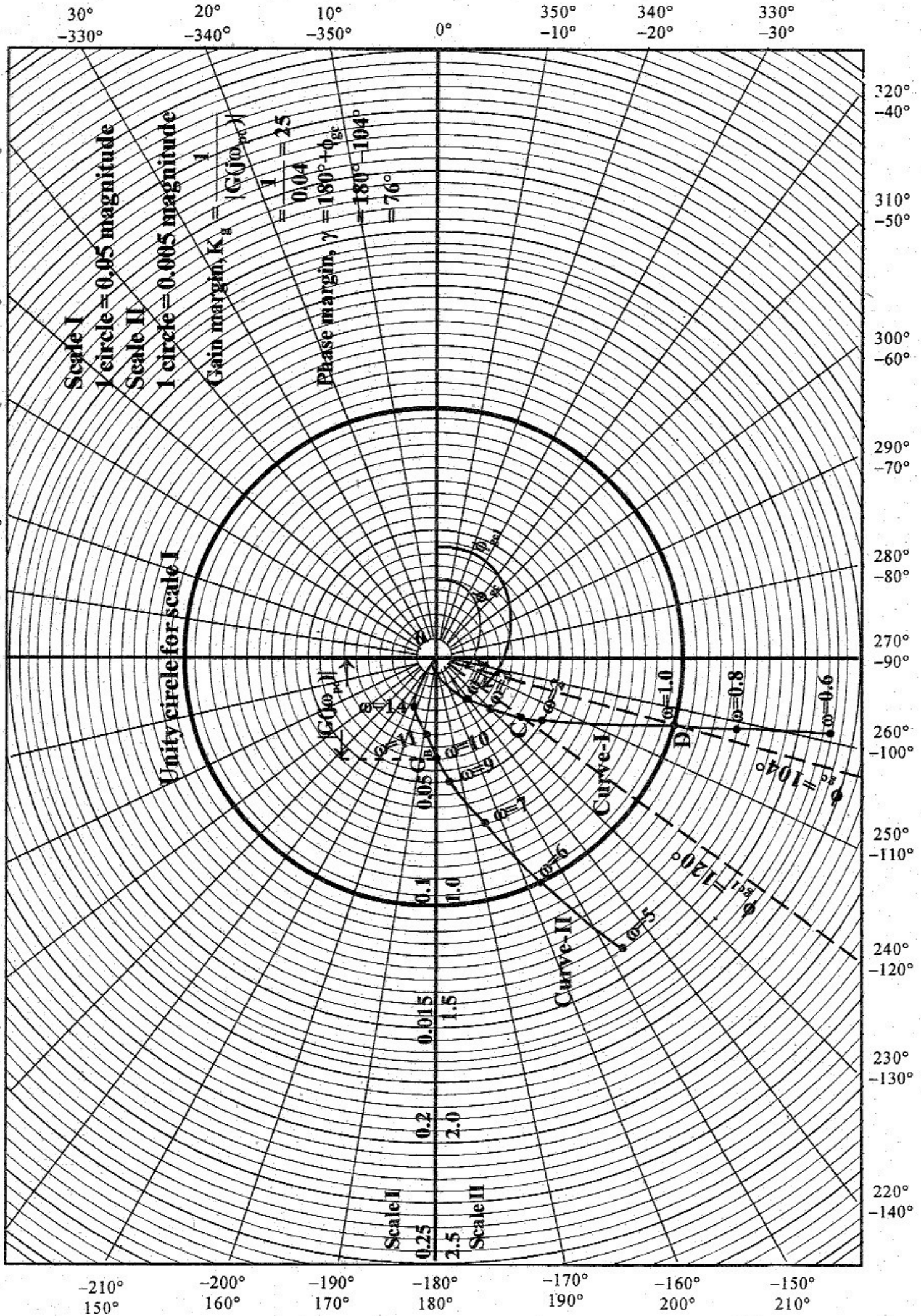


Fig 3.II.1: Polar plot of $G(j\omega) = 1/j\omega (1+j0.2\omega) (1+j0.05\omega)$, (using polar coordinates)

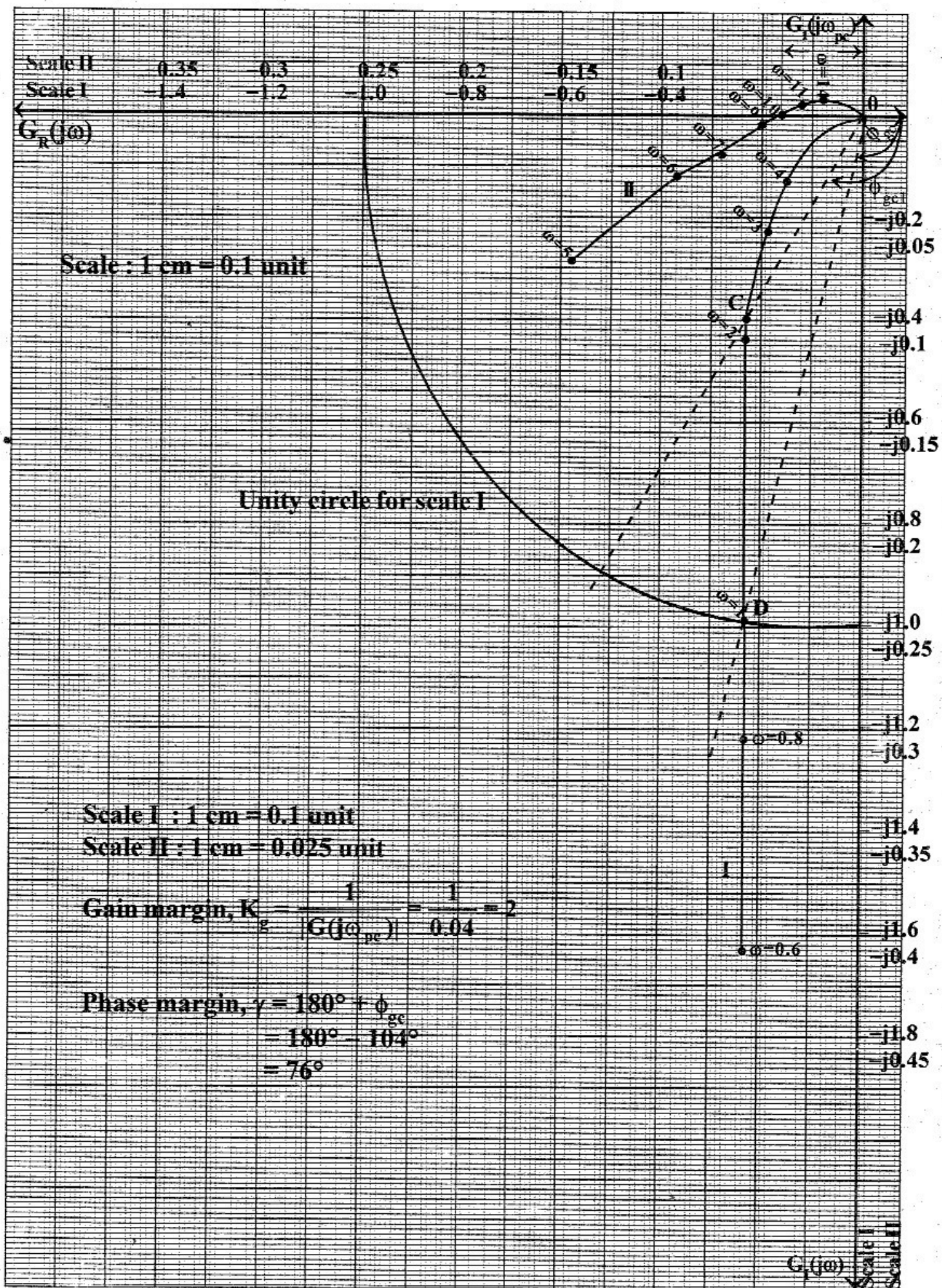


Fig 3.11.2: Polar plot of $G(j\omega) = 1/j\omega(1+j0.2\omega)(1+j0.05\omega)$, (using rectangular coordinates)

EXAMPLE 3.12

Consider a unity feedback system having an open loop transfer function, $G(s) = \frac{K}{s(1+0.5s)(1+4s)}$. Sketch the polar plot and determine the value of K so that (i) Gain margin is 20 db and (ii) Phase margin is 30° .

SOLUTION

Given that, $G(s) = K/s(1+0.5s)(1+4s)$

The polar plot is sketched by taking $K=1$.

Put $K=1$ and $s=j\omega$ in $G(s)$.

$$\therefore G(j\omega) = \frac{1}{j\omega(1+j0.5\omega)(1+j4\omega)}$$

The corner frequencies are $\omega_{c1} = 1/4 = 0.25$ rad/sec and $\omega_{c2} = 1/0.5 = 2$ rad/sec. The magnitude and phase angle of $G(j\omega)$ are calculated for various frequencies and tabulated in table-1. Using polar to rectangular conversion the polar coordinates listed in table-1 are converted to rectangular coordinates and tabulated in table-2. The polar plot using polar coordinates is sketched on a polar graph sheet as shown in fig 3.12.1. The polar plot using rectangular coordinates is sketched on an ordinary graph sheet as shown in fig 3.12.2.

$$\begin{aligned} G(j\omega) &= \frac{1}{j\omega(1+j0.5\omega)(1+j4\omega)} \\ &= \frac{1}{\omega \angle 90^\circ \sqrt{1+(0.5\omega)^2} \angle \tan^{-1} 0.5\omega \sqrt{1+(4\omega)^2} \angle \tan^{-1} 4\omega} \\ &= \frac{1}{\omega \sqrt{1+0.25\omega^2} \sqrt{1+16\omega^2}} \angle (-90^\circ - \tan^{-1} 0.5\omega - \tan^{-1} 4\omega) \\ \therefore |G(j\omega)| &= \frac{1}{\omega \sqrt{1+0.25\omega^2} \sqrt{1+16\omega^2}} \\ \angle G(j\omega) &= -90^\circ - \tan^{-1} 0.5\omega - \tan^{-1} 4\omega \end{aligned}$$

TABLE-1 : Magnitude and Phase of $G(j\omega)$ at Various Frequencies

ω rad/sec	0.3	0.4	0.5	0.6	0.8	1.0	1.2
$ G(j\omega) $	2.11	1.3	0.87	0.61	0.35	0.22	0.15
$\angle G(j\omega)$ deg	-149	-159	-167	-174	-184	-193	-199

TABLE-2 : Real part and Imaginary parts of $G(j\omega)$ at Various Frequencies

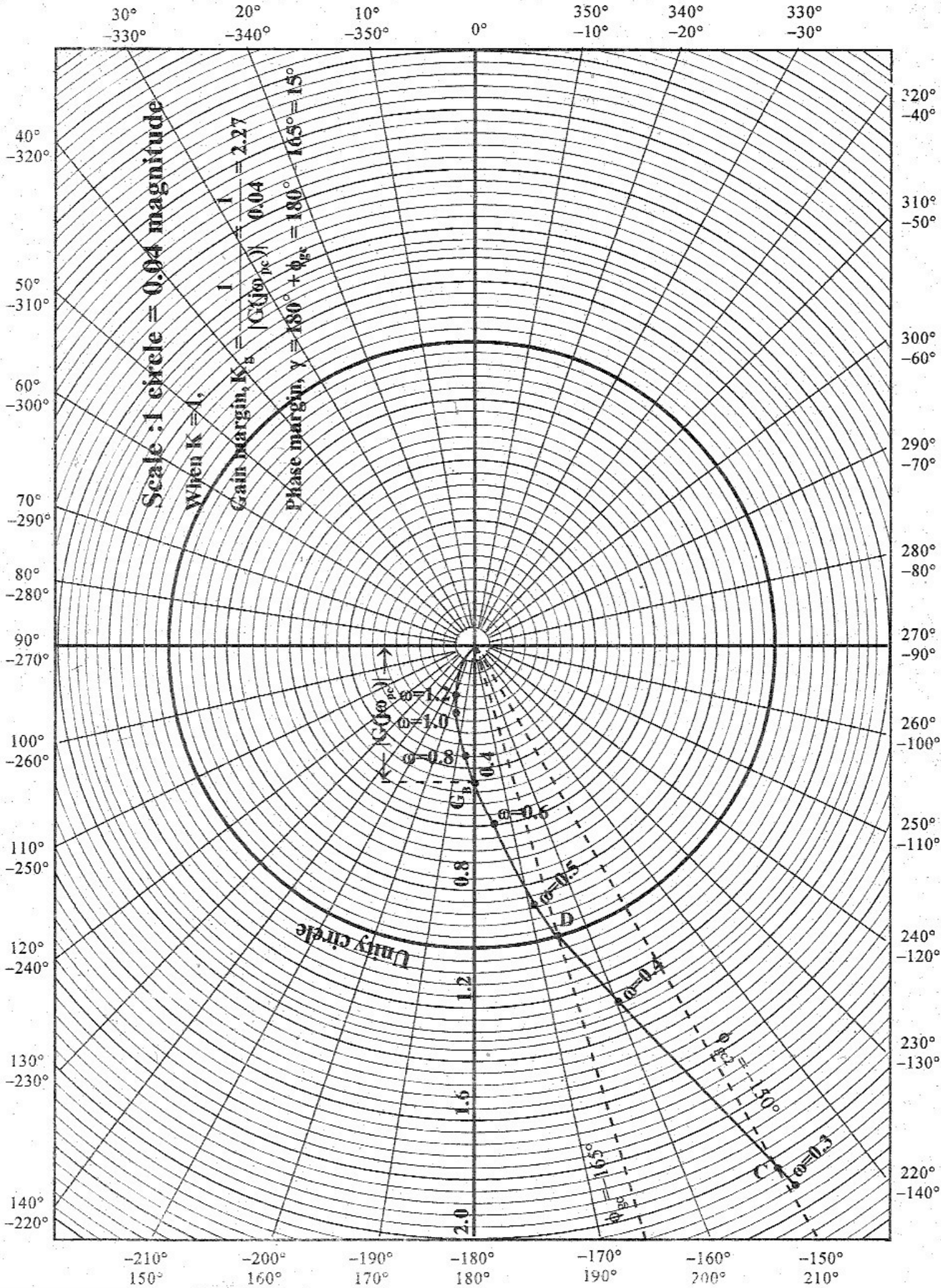
ω rad/sec	0.3	0.4	0.5	0.6	0.8	1.0	1.2
$G_R(j\omega)$	-1.8	-1.21	-0.85	-0.61	-0.35	-0.21	-0.14
$G_I(j\omega)$	-1.09	-0.47	-0.2	-0.06	0.02	0.05	0.05

From the polar plot, with $K=1$,

Gain margin, $K_g = 1/0.44 = 2.27$

Gain margin in db = $20 \log 2.27 = 7.12$ db

Phase margin, $\gamma = 180^\circ + \phi_{gc} = 180^\circ - 165^\circ = 15^\circ$



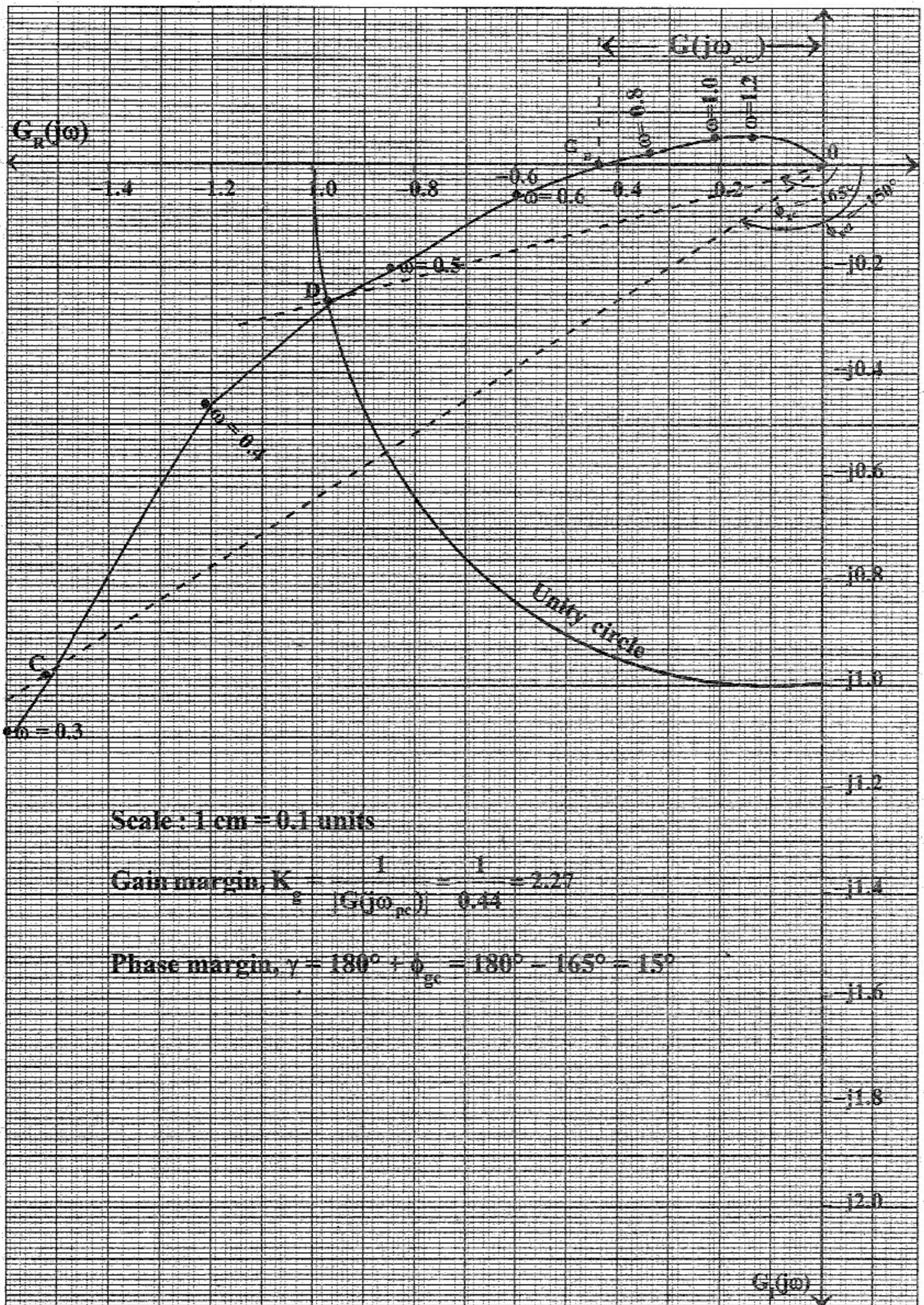


Fig 3.12.2: Polar plot of $G(j\omega) = 1/[j\omega(1+j0.5\omega)(1+j4\omega)]$, (using rectangular coordinates).